










## Accessories for 2.1010.0010

Below, the accessories are grouped into Scope of delivery and Optional accessories.  
Please keep this printout at hand for ordering replacement material.  
These lists may be subject to change.

### Scope of delivery 2.1010.0010

Qty.	Order no.	Description	
1 pcs	1.1010.0010	<b>Main module Pick&amp;Place S</b>	
		Main module for setting up an OMNIS Sample Robot Pick&Place in size S. This module is comprised of module and rack plates. It is already equipped with the main lift and one gripper. In addition to sample racks and gripper fingers, workstations such as Pick&Place module or a pump module are required for using it to set up a functioning Sample Robot. The selection of these components proceeds in accordance with the application.	
1 pcs	6.02706.000	<b>Cable cover for Sample Robot</b>	
		The cable cover protects the MDL and Ethernet cables connectors on the OMNIS Sample Robot.	

## Optional accessories

Order no.	Description	
<b>2.1014.0010</b>	<b>Pick&amp;Place module</b>	
	Module for installation in the module plate of the Pick&Place of the OMNIS Sample Robot. This workstation takes up the sample beaker for the analysis. Used sensors are cleaned or parked in the storage beaker of the Pick&Place module between analyses. If stirring is required during the analysis, then a separate rod stirrer must be used for this workstation.	
<b>2.1014.0110</b>	<b>Pick&amp;Place module with stirrer</b>	
	Module for installation in the module plate of the Pick&Place of the OMNIS Sample Robot. This workstation takes up the sample beaker for the analysis. The built-in magnetic stirrer makes it possible to analyze samples that were prepared externally on a magnetic agitator directly in the Sample Robot without having to remove the magnetic stirring bar beforehand. Used sensors are cleaned or parked in the storage beaker of the Pick&Place module between analyses.	
<b>2.1016.0010</b>	<b>Peristaltic (2-channel) pump module</b>	
	Module for installation in the module plate of the Pick&Place of the OMNIS Sample Robot. This workstation is equipped with both a rinsing pump and an aspiration pump. They are used to clean the sensors in a Pick&Place module and to empty the sample beaker after the analysis before it is returned to the rack once again.	
<b>2.1016.0110</b>	<b>Peristaltic (4-channel) pump module</b>	
	Module for installation in the module plate of the Pick&Place of the OMNIS Sample Robot. This workstation is equipped with two rinsing pumps and two aspiration pumps each. They are used to clean the sensors in two Pick&Place modules and to empty the sample beaker after the analysis before it is placed back in the rack once again.	
<b>6.02041.010</b>	<b>OMNIS sample rack 9 x 250 mL</b>	
	OMNIS sample rack 9 x 250 mL for use with 250 mL glass sample beaker (P&P) or 250 mL PP sample beaker (P&P)	
<b>6.02041.020</b>	<b>OMNIS sample rack 9 x 200 mL</b>	
	OMNIS 9 x 200 mL sample rack for use with disposable PP sample beaker.	
<b>6.02041.030</b>	<b>OMNIS sample rack 16 x 120 mL</b>	
	OMNIS sample rack 16 x 120 mL for use with 120 mL PP sample beaker	

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**6.02041.040                    OMNIS sample rack 25 x 75 mL**

OMNIS sample rack 25 x 75 mL for use with 75 mL glass sample beaker (P&P)




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**6.02041.050                    OMNIS sample rack 9 x 150 mL**

OMNIS sample rack 9 x 150 mL for the use of 150 mL beakers, tall shape, without spout.




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**6.02064.020                    Retainer for 200 mL sample beaker**

Retainer for fixing the 200 mL sample beaker in place in the gripper fingers of the OMNIS Sample Robot Pick&Place.




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**6.02600.000                    Dummy panel for module plate**

Dummy panel for covering open spaces on the module plate of the OMNIS Sample Robot




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**6.02601.010                    Gripper fingers 43 - 65 mm**

Gripper fingers for OMNIS Sample Robot Pick&Place for gripping sample beakers with an outer diameter of 43 to 65 mm.




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**6.02601.020                    Gripper fingers 50 - 72 mm**

Gripper fingers for OMNIS Sample Robot Pick&Place for gripping sample beakers with an outer diameter of 50 to 72 mm.




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**6.02601.030                    Gripper fingers 48-64 mm**

Gripper fingers for OMNIS Pick&Place Sample Robot for gripping sample beakers with an outer diameter of 48 - 64 mm.




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**6.02601.040                    Gripper fingers 28-48 mm**

Gripper fingers for OMNIS Sample Robot Pick&Place for gripping sample beakers with an outer diameter of 28 - 48 mm.



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**6.02602.000            Tubing duct to OMNIS Sample Robot**

Tubing duct for guiding the tubing between the pump module and canisters.



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**6.05700.000            Consumable Kit OMNIS Gripper**

Four slide sleeves and rubber gripper fingers each for replacement on the gripper finger of the OMNIS Sample Robot.



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**6.05700.250            Consumable Kit OMNIS Gripper for 6.02601.030**

Four rubber gripper fingers for replacement on the gripper finger of the OMNIS Sample Robot.



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**6.05800.000            Upgrade Sample Robot S to M**

The set contains all of the components required for upgrading an already existing OMNIS Sample Robot from size S to size M. In addition to the required rack and module bases, all of the required cables, screws and arm extensions are included, as is the function license.



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**6.05800.010            Upgrade Sample Robot S to L**

The set contains all of the components required for the upgrade of an already existing OMNIS Sample Robot from size S to size L. In addition to the required rack and module bases, all of the required cables, screws and arm extensions are included, as is the function license.

