Application Note AN-EC-004

Ohmic iR drop

Part 2 – Measurement: Current interrupt and positive feedback

In Application Note AN-EC-003, the concepts of ohmic drop (also called iR drop or uncompensated resistance) and ohmic resistance were explained and some strategies for reducing the errors due to the ohmic drop were discussed. By employing some of these strategies, the ohmic iR drop can be reduced but cannot be totally eliminated. Fortunately, further steps can be taken with a modern potentiostat, making it possible to measure the remaining iR drop and then compensate for it. However, only up to 90% of the ohmic iR drop can be compensated for.

This Application Note introduces two tools that researchers using Metrohm Autolab products have at their disposal in order to measure and then correct (or compensate) for ohmic iR drop—current interrupt and positive feedback.

In a potentiostat connected to a three-electrode cell setup, the potential between the working electrode (WE) and a reference electrode (RE) is controlled by means of a control loop. The desired potential difference between the RE and WE is maintained by adjusting the current flow between the counter (CE) and the working electrodes. The ohmic resistance R_u, also known as uncompensated resistance, causes a potential control error called ohmic drop iR_u. This control error can be corrected by adding a correction voltage proportional to the current flow to the input of the potentiostat. Unfortunately, it is not possible to use a correction potential exactly equal to iR_u and fully compensate the ohmic drop, because the system will go into oscillation.

The ohmic drop depends on the ohmic resistance R_u, which is a function of the cell geometry and the conductivity of the electrolyte. For a planar electrode with uniform current density across its surface, the ohmic resistance is given by the equation shown here, where X (cm) is the distance of the RE from the WE, κ (S cm^{-1}) is the solution conductivity, and A (cm^2) is the WE surface area.

$$R_u = \frac{X}{\kappa A}$$

For a spherical electrode (e.g., dropping mercury electrode / DME, or hanging dropping mercury electrode / HMDE) of radius r_0, the ohmic resistance is given by:

$$R_u = \frac{1}{4\pi\kappa r_0}\left(\frac{X}{X + r_0}\right)$$

For a rotating disc electrode (RDE) of radius r, when the RE is placed far from the working electrode (typically for RDE measurements), the ohmic resistance is given by:

$$R_u = \frac{1}{4\kappa r}$$

MEASURING THE OHMIC DROP

In most cases, the geometries are more complicated and consequently the ohmic drop must be measured experimentally. The three most common methods for measuring the ohmic drop are:

1. Current interrupt
2. Positive feedback
3. Electrochemical impedance spectroscopy (EIS, see AN-EC-034)

The electrical equivalent circuit shown in Figure 1 is used to illustrate the first two methods in the list above. This circuit corresponds to dummy cell circuit (c) of the Autolab dummy cell 2.

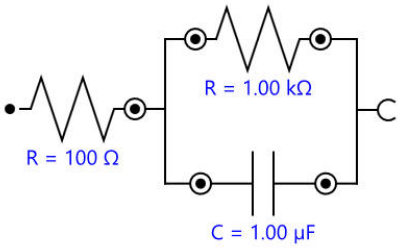


Figure 1. The equivalent circuit used in this study.

CURRENT INTERRUPT

The measurement of ohmic drop using the current interrupt technique is based on the simple application of Ohm's law. When a current i flows through the circuit mentioned in Figure 1, the voltage drop across the resistor R_u is equal to iR_u, and the voltage drop across (R_pC) is iR_p. If the current is interrupted, then i becomes 0 and the voltage across R_u drops almost instantaneously while the voltage across (R_pC) drops with an exponential decay proportional to $EXP(-t/R_pC)$, due to the presence of the capacitor C.

If the voltage is measured just before and immediately after the current has been interrupted, the difference in the measured voltages is the ohmic drop ΔE_{ohmic} . The ratio between the ohmic drop and the current before the interruption is the ohmic resistance R_u. The measurement of the ohmic drop for the dummy cell circuit (c, the equivalent circuit in Figure 1) using a PGSTAT302N with an ADC10M fast sampling module is illustrated in Figure 2.

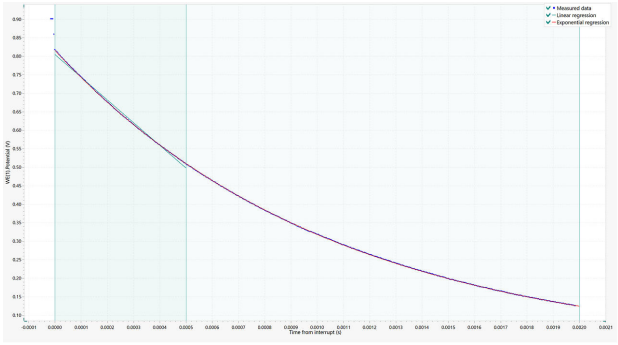


Figure 2. Measurement of ohmic resistance with current interrupt using a PGSTAT302N with the ADC10M.

If an ADC10M module is not available, the method can still be used. However, fewer data points will be recorded, resulting in a less accurate measurement (Figure 3).

The measured values are fitted using a linear and an exponential regression, and the calculated R_u values are displayed in the Results tab of the software (Figure 4).

Figure 3. Measurement of the ohmic resistance with current interrupt using the PGSTAT302N. Fewer data points are recorded compared to Figure 2.

The calculated values strongly depend on the specified start and stop positions for the linear and exponential regression. If these positions are not adjusted properly, the calculated values can be significantly different from the real uncompensated resistance. Note that there is no linear part in either Figure 2 or Figure 3, so the value fitted from the exponential regression should be taken as the more accurate value.

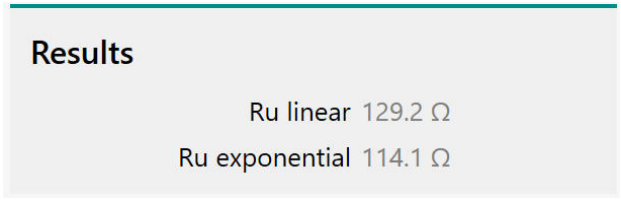


Figure 4. The resistance values obtained from the linear and exponential fitting of the data.

POSITIVE FEEDBACK

Another way to measure the ohmic drop is the so-called positive feedback. Since the ohmic drop iR_u is proportional to the ohmic resistance R_u, it might be possible to compensate for the ohmic drop by measuring the current i, multiplying it by the ohmic resistance R_u, and feeding back the resulting ohmic drop to the control loop. In this case, the following points need to be considered: the ohmic resistance is unknown at this stage, and a complete compensation of the ohmic drop would leave the system in oscillation – losing control of the potentiostat.

In the positive feedback measurement, a voltage iR_x is fed back into the control loop during a short potential step measurement. The goal is to find the value of R_x (the iR compensation value) close enough to the ohmic resistance R_u. This is accomplished by trial and error, i.e., repeating the procedure with different values of the iR compensation resistance and checking the resulting plot. An acceptable iR compensation results in damped oscillations of the signal, like the example shown in Figure 5.

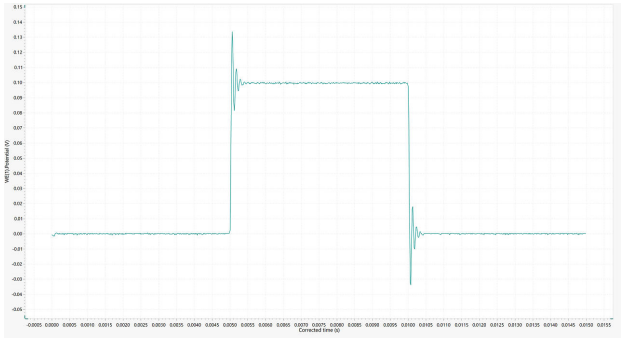


Figure 5. A positive feedback measurement of the circuit from Figure 1, dummy cell (c), with an acceptable iR compensation value of 95 Ω.

POSITIVE FEEDBACK

This method should be used with care. A system that oscillates is a system with more potential, and thus more energy, than necessary. Therefore, undesired side reactions could be triggered, affecting the electrolyte or damaging the working electrode.
The positive feedback can be directly measured in the NOVA software.

PRACTICAL COMPENSATION OF THE OHMIC DROP

Once the value of the ohmic resistance has been measured, it can be used in any desired NOVA procedure. In the properties of the Autolab control command, it is possible to toggle the «iR compensation» switch and insert the ohmic resistance value, as shown in Figure 6 .
The system will apply the iR compensation value similarly to the positive feedback method described earlier. Therefore, it is strongly recommended to use 80–90% of the ohmic resistance to avoid oscillations and damage to the WE and electrolyte.

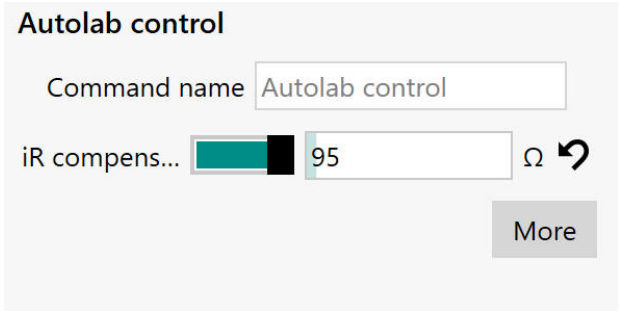


Figure 6. The properties of the Autolab control command in NOVA, with the iR compensation switch enabled.

Another way to use the ohmic drop is to perform one of the three discussed measurements, and then to use the value of the ohmic resistance to correct the experimental data mathematically.
The current *i* from the electrochemical experiment is multiplied by the ohmic resistance R_u in order to determine the ohmic drop $V_{drop} = i_{Ru}$. Then, V_{drop} is subtracted from the experimentally measured potential V_{exp}, resulting in the corrected potential $V_{corr} = V_{exp} - V_{drop}$. Finally, V_{corr} can be used in the plots and in further post-data treatments.

CONCLUSIONS

This Application Note describes two different methods of measuring the ohmic drop and the ohmic resistance. The ohmic drop can be compensated by the potentiostat during the measurement, or a mathematical correction can be applied to the data during post-processing.
Current interrupt and positive feedback are fast methods, but care is required for their use in order to avoid data misinterpretation or damage to the setup. On the other hand, EIS is a more reliable method to determine the ohmic resistance but requires the FRA32M optional module or VIONIC powered by INTELLO. The EIS method is explained separately in AN-EC-034.

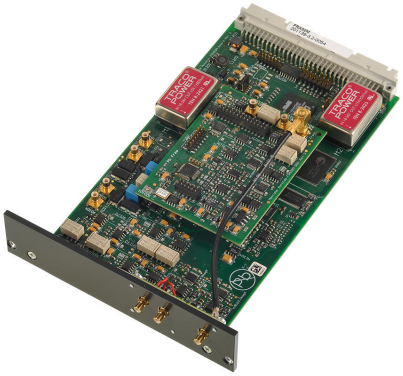
CONTACT

Metrohm Nordic ApS
Lyskær 3C. 1. th.
2730 Herlev
mail@metrohm.dk

CONFIGURATION

Autolab PGSTAT302N

This high end, high current potentiostat/galvanostat, with a compliance voltage of 30 V and a bandwidth of 1 MHz, combined with our FRA32M module, is specially designed for electrochemical impedance spectroscopy.
The PGSTAT302N is the successor of the popular PGSTAT30. The maximum current is 2 A, the current range can be extended to 20 A with the BOOSTER20A, the current resolution is 30 fA at a current range of 10 nA.



Dual-channel ultra-fast sampling module

The ADC10M module is an ultra-fast sampling module that increases the sampling rate of the Autolab from 50 kSamples/s to 10 MSamples/s giving you the ability to acquire fast transients with intervals down to 100 ns.

When combined with the SCAN250 module, you can perform ultra-fast cyclic voltammetry measurements with scan rates up to a practical limit of 250 kV/s, making it a powerful tool for studying fast kinetic processes.

Advanced software for electrochemical research

NOVA is the package designed to control all the Autolab instruments with USB interface.

Designed by electrochemists for electrochemists and integrating over two decades of user experience and the latest .NET software technology, NOVA brings more power and more flexibility to your Autolab potentiostat/galvanostat.

NOVA offers the following unique features:

- Powerful and flexible procedure editor
- Clear overview of relevant real-time data
- Powerful data analysis and plotting tools
- Integrated control for external devices like Metrohm Liquid Handling devices

Download the latest version of NOVA